

3.1

$$\begin{aligned}
 1) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix}\right) \\
 &= f\left(\begin{pmatrix} (v_1 + w_1) + (v_2 + w_2) \\ v_1 + w_1 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 + v_2 + w_2 \\ v_1 + w_1 \end{pmatrix}\right) \\
 \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = \begin{pmatrix} v_1 + v_2 \\ v_1 \end{pmatrix} + \begin{pmatrix} w_1 + w_2 \\ w_1 \end{pmatrix} \\
 &= \begin{pmatrix} v_1 + v_2 + w_1 + w_2 \\ v_1 + w_1 \end{pmatrix}
 \end{aligned}$$

Puisque les deux résultats sont égaux, on a que $f(\mathbf{v} + \mathbf{w}) = f(\mathbf{v}) + f(\mathbf{w})$.

$$\begin{aligned}
 \text{(b) i. } f(\alpha \mathbf{v}) &= f\left(\alpha \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} \alpha v_1 \\ \alpha v_2 \end{pmatrix}\right) = \begin{pmatrix} \alpha v_1 + \alpha v_2 \\ \alpha v_1 \end{pmatrix} \\
 \text{ii. } \alpha f(\mathbf{v}) &= \alpha f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) = \alpha \begin{pmatrix} v_1 + v_2 \\ v_1 \end{pmatrix} = \begin{pmatrix} \alpha(v_1 + v_2) \\ \alpha v_1 \end{pmatrix} = \begin{pmatrix} \alpha v_1 + \alpha v_2 \\ \alpha v_1 \end{pmatrix}
 \end{aligned}$$

Comme les résultats sont identiques, on a que $f(\alpha \mathbf{v}) = \alpha f(\mathbf{v})$.

L'application f est bien linéaire.

$$\begin{aligned}
 2) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix}\right) \\
 &= f\left(\begin{pmatrix} (v_1 + w_1) + 1 \\ 2(v_2 + w_2) \\ (v_1 + w_1) + (v_2 + w_2) \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 + 1 \\ 2v_2 + 2w_2 \\ v_1 + w_1 + v_2 + w_2 \end{pmatrix}\right) \\
 \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = \begin{pmatrix} v_1 + 1 \\ 2v_2 \\ v_1 + v_2 \end{pmatrix} + \begin{pmatrix} w_1 + 1 \\ 2w_2 \\ w_1 + w_2 \end{pmatrix} \\
 &= \begin{pmatrix} v_1 + w_1 + 2 \\ 2v_2 + 2w_2 \\ v_1 + v_2 + w_1 + w_2 \end{pmatrix}
 \end{aligned}$$

Les premières composantes diffèrent : $f(\mathbf{v} + \mathbf{w}) \neq f(\mathbf{v}) + f(\mathbf{w})$.

Inutile de tester la seconde propriété : l'application f n'est pas linéaire.

$$\begin{aligned}
 3) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \\ v_3 + w_3 \end{pmatrix}\right) \\
 &= 2(v_1 + w_1) - 3(v_2 + w_2) + 4(v_3 + w_3) \\
 &= 2v_1 + 2w_1 - 3v_2 - 3w_2 + 4v_3 + 4w_3 \\
 \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}\right) \\
 &= 2v_1 - 3v_2 + 4v_3 + 2w_1 - 3w_2 + 4w_3
 \end{aligned}$$

Puisque les deux résultats sont égaux, on a que $f(\mathbf{v} + \mathbf{w}) = f(\mathbf{v}) + f(\mathbf{w})$.

$$\text{(b) i. } f(\alpha \mathbf{v}) = f\left(\alpha \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) = f\left(\begin{pmatrix} \alpha v_1 \\ \alpha v_2 \\ \alpha v_3 \end{pmatrix}\right) = 2\alpha v_1 - 3\alpha v_2 + 4\alpha v_3$$

$$\text{ii. } \alpha f(\mathbf{v}) = \alpha f\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) = \alpha(2v_1 - 3v_2 + 4v_3) = 2\alpha v_1 - 3\alpha v_2 + 4\alpha v_3$$

Comme les résultats sont identiques, on a que $f(\alpha \mathbf{v}) = \alpha f(\mathbf{v})$.

L'application f est bien linéaire.

$$\begin{aligned} 4) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix}\right) = \begin{pmatrix} \sin(v_1 + w_1) \\ v_2 + w_2 \end{pmatrix} \\ \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = \begin{pmatrix} \sin(v_1) \\ v_2 \end{pmatrix} + \begin{pmatrix} \sin(w_1) \\ w_2 \end{pmatrix} \\ &= \begin{pmatrix} \sin(v_1) + \sin(w_1) \\ v_2 + w_2 \end{pmatrix} \end{aligned}$$

Les premières composantes diffèrent : $f(\mathbf{v} + \mathbf{w}) \neq f(\mathbf{v}) + f(\mathbf{w})$.

Inutile de tester la seconde propriété : l'application f n'est pas linéaire.

$$\begin{aligned} 5) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix}\right) \\ &= \begin{pmatrix} (v_1 + w_1)^2 \\ (v_1 + w_1) + (v_2 + w_2) \end{pmatrix} = \begin{pmatrix} v_1^2 + 2v_1w_1 + w_1^2 \\ v_1 + w_1 + v_2 + w_2 \end{pmatrix} \\ \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = \begin{pmatrix} v_1^2 \\ v_1 + v_2 \end{pmatrix} + \begin{pmatrix} w_1^2 \\ w_1 + w_2 \end{pmatrix} \\ &= \begin{pmatrix} v_1^2 + w_1^2 \\ v_1 + v_2 + w_1 + w_2 \end{pmatrix} \end{aligned}$$

Les premières composantes diffèrent : $f(\mathbf{v} + \mathbf{w}) \neq f(\mathbf{v}) + f(\mathbf{w})$.

Inutile de tester la seconde propriété : l'application f n'est pas linéaire.

$$\begin{aligned} 6) \text{ (a) i. } f(\mathbf{v} + \mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}\right) = f\left(\begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \\ v_3 + w_3 \end{pmatrix}\right) \\ &= \begin{pmatrix} 0 \\ v_1 + w_1 \\ 2(v_1 + w_1) \end{pmatrix} = \begin{pmatrix} 0 \\ v_1 + w_1 \\ 2v_1 + 2w_1 \end{pmatrix} \\ \text{ii. } f(\mathbf{v}) + f(\mathbf{w}) &= f\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) + f\left(\begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}\right) \\ &= \begin{pmatrix} 0 \\ v_1 \\ 2v_1 \end{pmatrix} + \begin{pmatrix} 0 \\ w_1 \\ 2w_1 \end{pmatrix} = \begin{pmatrix} 0 \\ v_1 + w_1 \\ 2v_1 + 2w_1 \end{pmatrix} \end{aligned}$$

Puisque les deux résultats sont égaux, on a que $f(\mathbf{v} + \mathbf{w}) = f(\mathbf{v}) + f(\mathbf{w})$.

$$(b) \text{ i. } f(\alpha \mathbf{v}) = f\left(\alpha \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) = f\left(\begin{pmatrix} \alpha v_1 \\ \alpha v_2 \\ \alpha v_3 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ \alpha v_1 \\ 2\alpha v_1 \end{pmatrix}$$

$$\text{ii. } \alpha f(\mathbf{v}) = \alpha f \left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \right) = \alpha \begin{pmatrix} 0 \\ v_1 \\ 2v_1 \end{pmatrix} = \begin{pmatrix} 0 \\ \alpha v_1 \\ 2\alpha v_1 \end{pmatrix}$$

Comme les résultats sont identiques, on a que $f(\alpha \mathbf{v}) = \alpha f(\mathbf{v})$.

L'application f est bien linéaire.